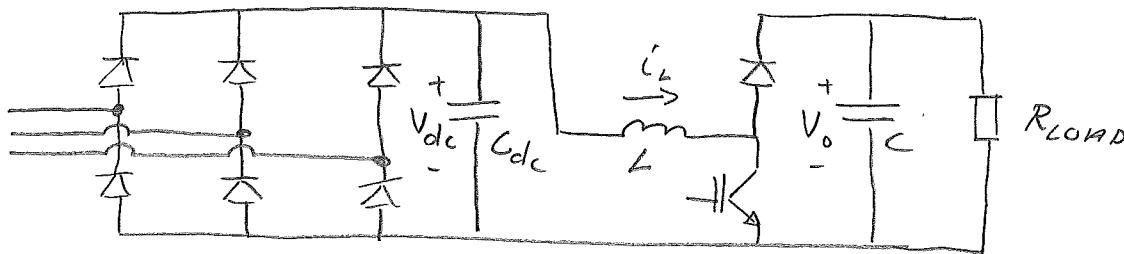


1.a)



b)

$$\begin{aligned}
 V_{dc} &= \frac{1}{T/6} \int_{T/6}^{\pi/6} \hat{U}_{LL} \cos(\omega t) dt = \frac{1}{T/6} \int_{T/6}^{\pi/6} \hat{U}_{LL} \cos(\omega t) d\omega \cdot \omega \cdot \frac{1}{\omega} = \\
 &= \frac{1}{\omega T/6} \int_{-\pi/6}^{\pi/6} \hat{U}_{LL} \cos(\omega t) d(\omega t) = \frac{6}{\omega T} \left[ \hat{U}_{LL} \sin(\omega t) \right]_{-\pi/6}^{\pi/6} = \\
 &= \left\{ \omega T = 2\pi \right\} = \frac{\hat{U}_{LL}}{2\pi} \left( \sin\left(\frac{\pi}{6}\right) - \sin\left(-\frac{\pi}{6}\right) \right) = \\
 &= \frac{6}{2\pi} \hat{U}_{LL} \underbrace{2\sin\frac{\pi}{6}}_{=1/2} = \frac{3 \cdot \sqrt{2}}{\pi} \cdot U_{LL\text{rms}} = 1,35 \cdot U_{LL\text{rms}} \\
 &= 1,35 \cdot 230 = \underline{\underline{310,5}}
 \end{aligned}$$

$$G \quad T = T_{ILL}: \quad V_{dc} - L \frac{di}{dt} = 0 \Rightarrow 4i = \frac{V_{dc}}{L} t_T = \frac{V_{dc}}{L} \delta_T T_{sw}$$

$$T = FRKAN: \quad V_{dc} - L \frac{di}{dt} - V_o = 0 \Rightarrow V_{dc} - L \frac{-|\Delta i|}{\Delta t} - V_o = 0$$

$$|\Delta i| = \frac{V_o - V_{dc}}{L} t_D = \frac{V_o - V_{dc}}{L} (1 - \delta_T) T_{sw}$$

$$\Delta KHEIT: \quad \frac{V_{dc}}{X} \delta_T T_{sw} = \frac{V_o - V_{dc}}{X} (1 - \delta_T) T_{sw}$$

$$\delta_T = \frac{V_o - V_{dc}}{V_o} = 1 - \frac{V_{dc}}{V_o} = 1 - \frac{310}{500} = \underline{\underline{0,38}}$$

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1. d)  $T = T_{LL} : \Delta i = \frac{V_{dc}}{L} \delta_T T_{sw} = \frac{310}{1,5 \cdot 10^{-3}} \cdot 0,38 \cdot \frac{1}{40 \text{ kHz}} = 1,96 A$

e)  $V_{dc} = 1,35 \cdot U_{LL} \cos \alpha$

$$\cos \alpha = 0,5 \Rightarrow \alpha = \arccos(0,5) = 60^\circ$$

$\lambda_C$ IGBT

$$R_{Th,jh} = 0,075 + 0,038 = 0,113$$

$$\begin{aligned} T_{Th\max, IGBT} &= T_f - R_{Th,jh} \cdot P_{Loss, IGBT} = \\ &= 125 - 0,113 \cdot 662 W = 50^\circ C \end{aligned}$$

FWD

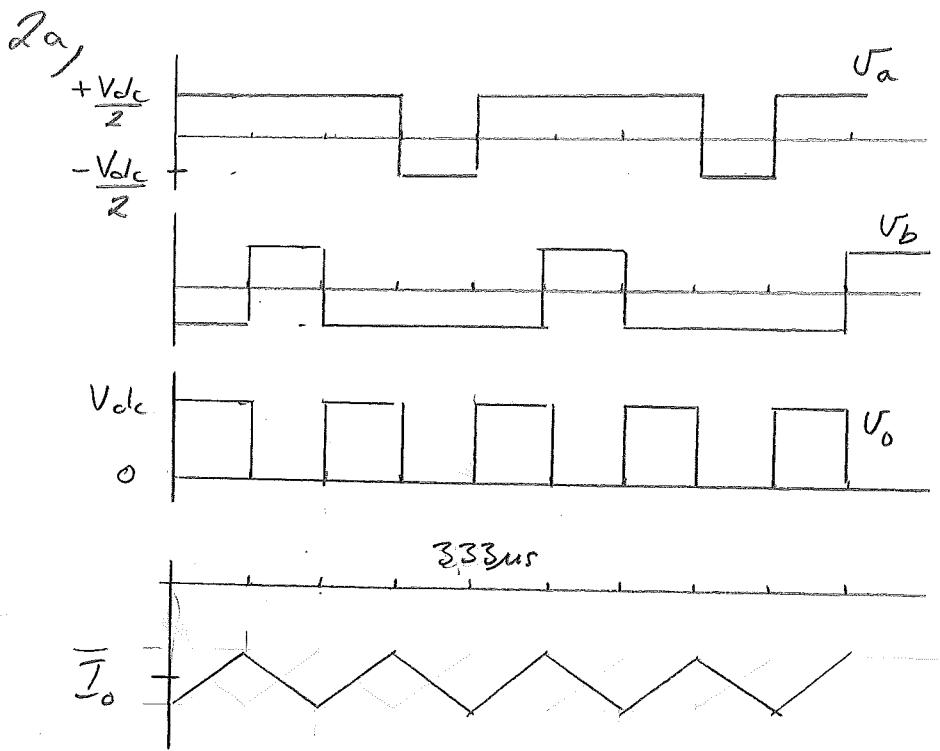
$$R_{Th,jh} = 0,18 \cdot 0,038 = 0,218$$

$$\begin{aligned} T_{Th\max, FWD} &= T_f - R_{Th,jh} \cdot P_{Loss, FWD} = \\ &= 125 - 0,218 \cdot 24,8 = 119,6^\circ C \end{aligned}$$

$$IGBT \text{ Segränsor} \Rightarrow T_{Th\max} = 50^\circ C$$

$$\begin{aligned} P_{Loss, \text{TOT}} &= 2(P_{Loss, IGBT} + P_{Loss, FWD}) = \\ &= 2 \cdot (662 + 24,8) = 1374 W \end{aligned}$$

$$R_{Th,ha} = \frac{T_{Th\max} - T_a}{P_{Loss, \text{TOT}}} = \frac{50 - 40}{1374} = 0,007 \text{ } ^\circ C/W$$



b)  $\frac{IGBT}{Fig 1} \Rightarrow V_{CE(on)} = 3,4V$  und  $150A$

$$P_{cond} = V_{CE(on)} \cdot I_c \cdot \delta_T = 3,4 \cdot 150 \cdot 0,99 = 505W$$

Fig 4  $\Rightarrow E_{on} = 41mJ$  und  $600V, 200A$

$E_{off} = 15mJ$  und  $600V, 200A$

$$P_{on} = 41 \cdot 10^{-3} \cdot \frac{750}{600} \cdot \frac{150}{200} \cdot 3kHz = 115W$$

$$P_{off} = 15 \cdot 10^{-3} \cdot \frac{750}{600} \cdot \frac{150}{200} \cdot 3kHz = 42W$$

$$P_{LOSS, IGBT} = P_{cond} + P_{on} + P_{off} = 505 + 115 + 42 = 662W$$

### FWD

Fig 11  $\Rightarrow V_{D(on)} = 1,55V$  und  $150A$

$$P_{cond} = V_{D(on)} \cdot I_D \cdot \delta_D = 1,55 \cdot 150 \cdot 0,01 = 2,3W$$

Fig 4  $\Rightarrow E_{rr} = 8mJ$  und  $600V, 200A$

$$P_{rr} = 8 \cdot 10^{-3} \cdot \frac{750}{600} \cdot \frac{150}{200} \cdot 3kHz = 22,5W$$

$$P_{LOSS, FWD} = P_{cond} + P_{rr} = 2,3 + 22,5 = 24,8W$$

$$3 \text{ a) } T=TI_{KL}: V_{dc} - \Delta m' \frac{di_1}{dt} = 0$$

$$\Delta i = \frac{V_{dc}}{\Delta m'} \delta_T T_{sw}$$

$$T=FRÄN: -\Delta m'' \frac{d\bar{i}_2}{dt} - V_o = 0$$

$$\frac{d\bar{i}_2}{dt} \approx -\frac{(\Delta \bar{i}_2)}{\Delta t} = \{ccm\}$$

$$= -\frac{(\Delta \bar{i}_2)}{(1-\delta_T) T_{sw}}$$

$$|\Delta \bar{i}_2| = \frac{V_o}{\Delta m''} (1-\delta_T) T_{sw}$$

$$\bar{i}_2 = \frac{N_1}{N_2} \bar{i}_1 \quad \left. \right\} \Rightarrow$$

$$\Delta m'' = \left( \frac{N_2}{N_1} \right)^2 \Delta m'$$

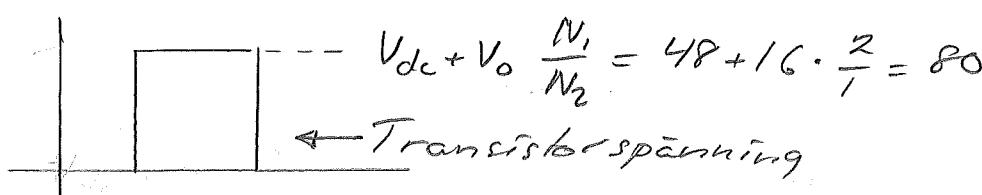
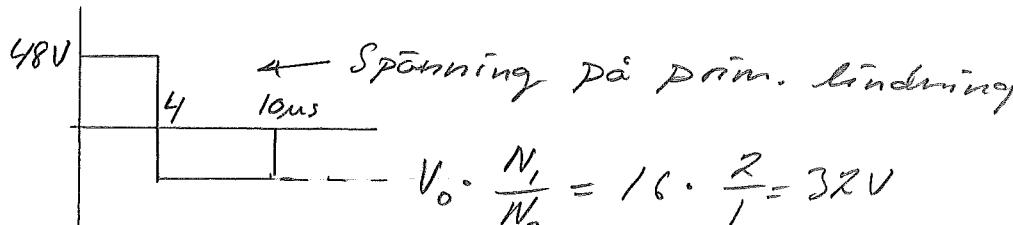
$$\frac{N_1}{N_2} \Delta \bar{i}_1 = \frac{V_o}{\left( N_2 / N_1 \right)^2 \Delta m'} (1-\delta_T) T_{sw}$$

$$\Delta \bar{i}_1 = \frac{V_o}{N_2 / N_1 \Delta m'} (1-\delta_T) T_{sw}$$

$$LIKET: \frac{V_{dc}}{\Delta m'} \delta_T T_{sw} = \frac{V_o}{N_2 / N_1 \Delta m'} (1-\delta_T) T_{sw}$$

$$V_o = \frac{N_2}{N_1} V_{dc} \frac{\delta_T}{1-\delta_T} = \frac{1}{2} \cdot 48 \frac{0,4}{1-0,4} = 16 \text{ V}$$

5)



3c)

T=TLL

$$\Delta \bar{I}_1 = \frac{V_{dc}}{L_m} \cdot \delta T_{sw} = \frac{48}{100 \cdot 10^{-6}} \cdot 0,41 \cdot 10 \cdot 10^{-6} = 1,92 A$$

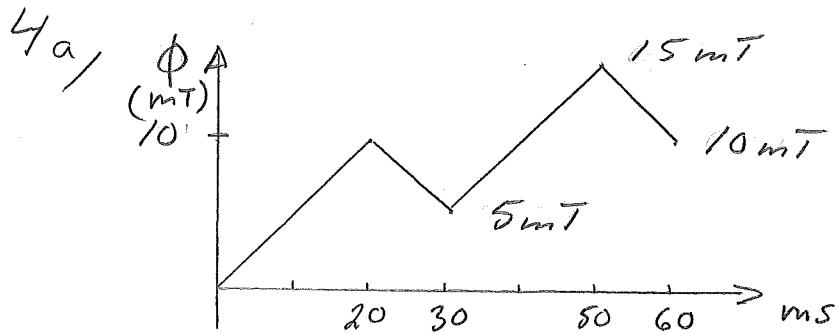
$$\hat{\bar{I}}_1 = \bar{I}_1 + \frac{\Delta \bar{I}_1}{2} = 1,4 + \frac{1,92}{2} = 2,36 A$$

- d) När transistorn är full kommet hela lastströmmen från kondensatoren.  $V_{out}$  faller under denna tid.

$$\bar{I}_c = C \frac{dV_c}{dt}$$

$$C = \bar{I}_c \frac{\Delta t}{\Delta V_c} = \bar{I}_o \frac{\Delta t}{\Delta V_{out}} =$$

$$= 2,8 \cdot 0,6 \frac{4 \cdot 10^{-6}}{0,01 \cdot 16} = 42 \mu F$$



$$U_L = N \frac{d\phi}{dt}$$

$$\phi = \frac{1}{N} \int U_L dt$$

på 20 ms ökar flödet:  $\Delta\phi = \frac{1}{10} \cdot 5V \cdot 20ms = 10mT$

på 10 ms minskar flödet:  $\Delta\phi = \frac{1}{10} \cdot (-5V) \cdot 20ms = -5mT$

Vid 60 ms är flödet  $\phi = 10mT$

b)

$$i = \frac{N\phi}{L} = \frac{10 \cdot 10mT}{25mH} = 4A$$

c)

Fördel: Mindre filterkomponenter

Nackdel: Större förlusor

d)

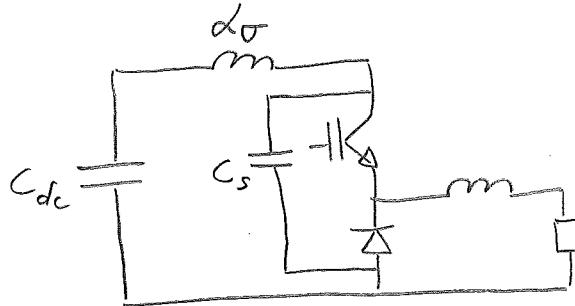
Fördel: Snabbare omslag  $\Rightarrow$  lägre svarstidsförlusor

Nackdel: Högre spänningssderivator  $\Rightarrow$  mer störningar

e)

Eftersom source på den övre transistorn varierar mellan 0V och ~Vdc. Kanske också även den övre drivarens spänning röra sig lika mycket upp och ned. Nedre drivarens spänning ligger ställa i förhållande till mellanledet.

5a)



b)

Ehr. vid translag

$$C_{dc} \frac{1}{T} \quad \frac{1}{T} C_s \Rightarrow \frac{1}{T} C_{eq}$$

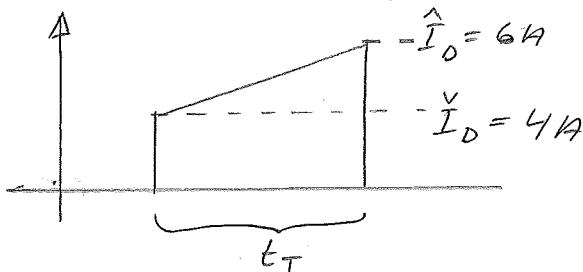
$$C_{dc} \gg C_s \Rightarrow C_{eq} \approx C_s$$

Energén i  $\alpha_0$  ska tas upp av  $C_s$ 

~~$$\frac{1}{2} \alpha_0 I_0^2 = \frac{1}{2} C_{eq} \cdot \Delta U_{Cs}^2 \Rightarrow$$~~

$$\Delta U_{Cs} = \sqrt{\frac{\alpha_0 I_0^2}{C_{eq}}} = 28 \text{ V}$$

c)



$$P_{cond} = \frac{1}{T} \int_0^{t_f} \underbrace{R_{DS(on)}}_{U_{DS}} \cdot \bar{i}_D(t) \cdot \dot{i}_D(t) dt =$$

$$= \frac{1}{T} \int_0^{t_f} R_{DS(on)} \left( \bar{i}_D + \frac{\Delta \bar{i}_D}{t_f} \cdot t \right)^2 dt =$$

$$= \frac{1}{T} \int_0^{t_f} R_{DS(on)} \left( \bar{i}_D^2 + 2 \bar{i}_D \frac{\Delta \bar{i}_D}{t_f} \cdot t + \left( \frac{\Delta \bar{i}_D}{t_f} \right)^2 t^2 \right) dt =$$

$$= \frac{R_{DS(on)}}{\tau} \left[ \overset{\vee}{I_D}^2 \cdot t + \overset{\vee}{I_D} \cdot \frac{\Delta \overset{\wedge}{I_D}}{t_r} t^2 + \left( \frac{\Delta \overset{\wedge}{I_D}}{t_r} \right)^2 \cdot \frac{t^3}{3} \right]_0^{t_r} =$$

$$= R_{DS(on)} \left( \overset{\vee}{I_D}^2 + \overset{\vee}{I_D} \Delta \overset{\wedge}{I_D} + \frac{\Delta \overset{\wedge}{I_D}^2}{3} \right) \frac{t_r}{\tau}$$

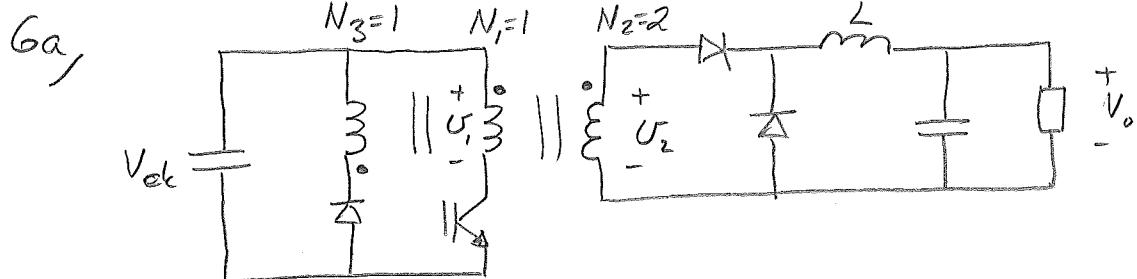
$$= \frac{1,9}{10} \left( 4^2 + 4 \cdot 2 + \frac{2^2}{3} \right) \cdot 0,8 = \underline{\underline{3,85W}}$$

d)  $P_{SW,ON} = \frac{V_{de} \cdot \overset{\wedge}{I_D}}{2} \cdot t_{turn\ on} \cdot f_{sw} =$

$$= \frac{100 \cdot 4}{2} \cdot 100 \cdot 10^{-9} \cdot 10 \text{kHz} = \underline{\underline{0,2W}}$$

$$P_{SW,OFF} = \frac{V_{de} \cdot \overset{\wedge}{I_D}}{2} \cdot t_{turn\ off} \cdot f_{sw} =$$

$$= \frac{100 \cdot 6}{2} \cdot 100 \cdot 10^{-9} \cdot 10 \text{kHz} = \underline{\underline{0,3W}}$$



b) T=TILL

$$U_2 - L \frac{di_L}{dt} - U_o = 0 \quad \{ U_2 = \frac{N_2}{N_1} \cdot U_1 = 2 V_{dc} \}$$

$$2 V_{dc} - L \frac{\Delta i_L}{\Delta t} - U_o = 0 \Rightarrow \Delta i_L = \frac{2 V_{dc} - U_o}{L} \delta_T T_{sw}$$

T=FRAÖN

$$0 - L \frac{di_L}{dt} - U_o = 0 \Rightarrow -L \frac{-|\Delta i_L|}{\Delta t} - U_o = 0 \Rightarrow \{ CCM \} \Rightarrow$$

$$|\Delta i_L| = \frac{U_o}{L} (1 - \delta_T) T_{sw}$$

LIKHET

$$\frac{2 V_{dc} - U_o}{L} \delta_T T_{sw} = \frac{U_o}{L} (1 - \delta_T) T_{sw}$$

$$\delta_T = \frac{U_o}{2 \cdot V_{dc}} = \frac{24}{2 \cdot 90} = 0,13$$

c) Maximal spänning fås vid max  $\delta$   
max  $\delta$  bestäms av armagnetseringen

T=TILL

$$V_{dc} - d_m' \frac{\Delta \tilde{i}_m'}{\Delta t} = 0 \Rightarrow \Delta \tilde{i}_m' = \frac{V_{dc} \Delta t}{d_m'}$$

T=FRAÖN

$$V_{dc} - d_m''' \frac{\Delta \tilde{i}_m'''}{\Delta t} = 0 \quad \left. \begin{aligned} d_m''' &= d_m' \left( \frac{N_3}{N_1} \right)^2 \\ \Delta \tilde{i}_m''' &= \Delta \tilde{i}_m' \frac{N_1}{N_2} \end{aligned} \right\} \Rightarrow$$

$$V_{dc} - \Delta i_m' \left( \frac{N_3}{N_1} \right)^2 - \frac{\Delta i_m' \left( \frac{N_1}{N_3} \right)}{\Delta t} = 0$$

LIKHET

$$\frac{V_{dc}}{\Delta t} \delta_T \tau_{sw} = \frac{V_{dc}}{\Delta t} \frac{N_1}{N_3} \left( 1 - \delta_T \right) \tau_{sw}^{\text{CCM}}$$

$$\delta_T = \frac{N_1}{N_3} - \frac{N_1}{N_3} \delta_T$$

$$\delta_{T\max} = \frac{N_1/N_3}{1 + N_1/N_3} = \frac{1}{1+1} = 0,5$$

↓ enl. uppg 6)

$$V_{o\max} = \delta_{T\max} \cdot 2 V_{dc} = 0,5 \cdot 2 \cdot 90 = \underline{\underline{90 \text{ V}}}$$

d. Lägsta lasten är mest kritisk

$$\bar{I}_{o\min} = \frac{P_{o\min}}{V_o} = \frac{25}{24} = 1,04 \text{ A}$$

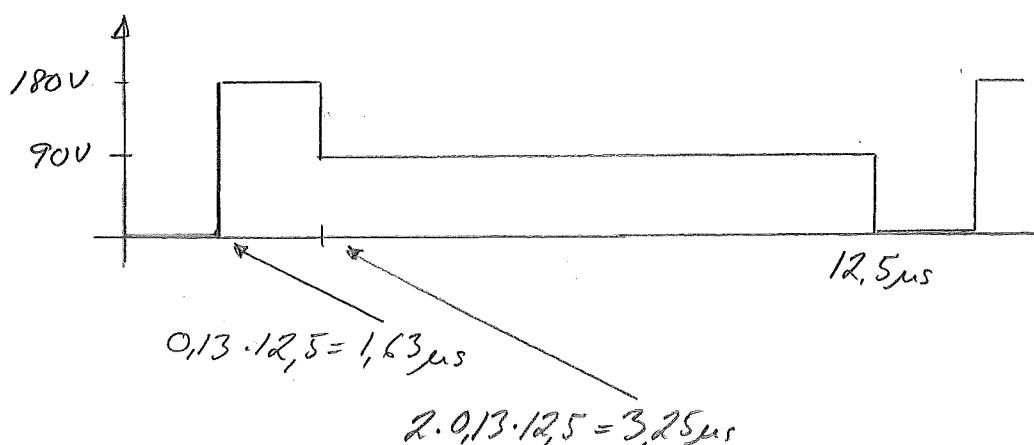
T=TILL

$$\Delta i_L = \frac{2 V_{dc} - V_o}{2} \delta_T \tau_{sw}$$

$$\alpha = \frac{2 V_{dc} - V_o}{\Delta i_L} \delta_T \tau_{sw} = \frac{2 V_{dc} - V_o}{2 \bar{I}_o} \delta_T \tau_{sw} =$$

$$= \frac{2 \cdot 90 - 24}{2 \cdot 1,04} \cdot 0,13 \cdot \frac{1}{80 \text{ kHz}} = \underline{\underline{122 \mu\text{H}}}$$

e.



f)

Transformatorn kan inte armagnetiseras på sek. eftersom dioden blockerar alltså kommer tråden magnetiseras mer och mer för varje switchperiod. Till slut mätter tråden.