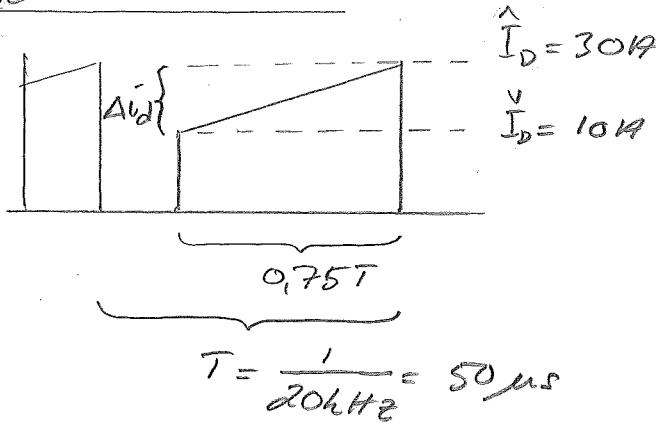


BWW 5.6

$$t_{\text{turn-on}} = t_{\text{tri}} + t_{\text{ftr}} = 100\text{ ns}$$

$$t_{\text{turn-off}} = t_{\text{ftr}} + t_{\text{tri}} = 200\text{ ns}$$

$$P_{\text{sw,ON}} = \frac{V_{\text{de}} \cdot I_d}{2} \cdot t_{\text{turn-on}} \cdot f_{\text{sw}} = \frac{340 \cdot 10}{2} \cdot 100 \cdot 10^{-9} \cdot 20 \cdot 10^3 = 3,4\text{ W}$$

$$P_{\text{sw,OFF}} = \frac{V_{\text{de}} \cdot I_d}{2} \cdot t_{\text{turn-off}} \cdot f_{\text{sw}} = \frac{340 \cdot 30}{2} \cdot 200 \cdot 10^{-9} \cdot 20 \cdot 10^3 = 20,4\text{ W}$$

$$P_{\text{sw}} = P_{\text{sw,ON}} + P_{\text{sw,OFF}} = 3,4 + 20,4 = \underline{\underline{23,8\text{ W}}}$$

$$\begin{aligned}
 \text{(ii)} \quad P_{\text{cond}} &= \frac{1}{T} \int_0^{t_T} \underbrace{R_{\text{DS(ON)}}}_{U_{\text{DS}}} \cdot \bar{c}_D(t) \cdot \bar{i}_D(t) \, dt = \\
 &= \frac{1}{T} \int_0^{t_T} R_{\text{DS(ON)}} \cdot \left(\bar{I}_d + \frac{\Delta \bar{i}_d}{t_T} \cdot t \right)^2 \, dt = \\
 &= \frac{1}{T} \int_0^{t_T} R_{\text{DS(ON)}} \left(\bar{I}_d^2 + 2\bar{I}_d \cdot \frac{\Delta \bar{i}_d}{t_T} \cdot t + \left(\frac{\Delta \bar{i}_d}{t_T} \right)^2 \cdot t^2 \right) \, dt = \\
 &= \frac{R_{\text{DS(ON)}}}{T} \left[\frac{\bar{I}_d^2}{2} \cdot t + \bar{I}_d \frac{\Delta \bar{i}_d}{t_T} \cdot t^2 + \left(\frac{\Delta \bar{i}_d}{t_T} \right)^2 \frac{t^3}{3} \right]_0^{t_T} = \\
 &= R_{\text{DS(ON)}} \underbrace{\left(\bar{I}_d^2 + \bar{I}_d \Delta \bar{i}_d + \frac{\Delta \bar{i}_d^2}{3} \right)}_{I_{\text{D,RMS}}^2} \frac{t_T}{T} = \\
 &= 0,1 \left(10^2 + 10 \cdot 20 + \frac{20^2}{3} \right) 0,75 = \underline{\underline{32,5\text{ W}}}
 \end{aligned}$$

iii) $T_a = 40^\circ\text{C}$

$$\begin{aligned}T_f &= P_{\text{loss}} \cdot R_{Th, ja} + T_a = \\&= P_{\text{loss}} (R_{Th, jc} + R_{Th, ca}) + T_a = \\&= (23,8 + 32,5) (0,4 + 0,6) + 40 = 96,3^\circ\text{C}\end{aligned}$$